

CONCUR 2023 – ANTWERP BELGIUM

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Safety and Liveness of Quantitative Automata

Boolean Properties

Definition

A Boolean property $\Phi \subseteq \Sigma^\omega$ or equivalently $\Phi: \Sigma^\omega \rightarrow \{0, 1\}$, is a language

Safety

Requests Not Duplicated

Liveness

All Requests Granted

Boolean Properties

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Safety

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Liveness

All Requests Granted

Theorem: Decomposition¹

All Boolean property Φ can be expressed by $\Phi = \Phi_{safe} \cap \Phi_{live}$

- ▶ Φ_{safe} is safe
- ▶ Φ_{live} is live

¹ Alpern, Schneider. *Defining liveness*. 1985

Quantitative Properties

Definition

A quantitative property² $\Phi: \Sigma^\omega \rightarrow \mathbb{D}$ is a quantitative language where \mathbb{D} is a complete lattice

² Chatterjee, Doyen, Henzinger. *Quantitative Languages*. 2010

Quantitative Properties

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A quantitative property $\Phi: \Sigma^\omega \rightarrow \mathbb{D}$ is a quantitative language where \mathbb{D} is a complete lattice

Safety³

Minimal Response Time

Liveness³

Average Response Time

Theorem: Decomposition³

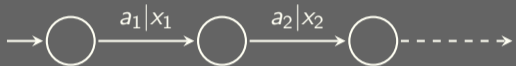
All quantitative property Φ can be expressed by $\Phi(w) = \min\{\Phi_{safe}(w), \Phi_{live}(w)\}$ for all $w \in \Sigma^\omega$

- ▶ Φ_{safe} is quantitative safe
- ▶ Φ_{live} is quantitative live

³ Henzinger, Mazzocchi, Saraç. *Quantitative Safety and Liveness*. 2023

Quantitative Automata

Runs



Word: $w = a_1 a_2 \dots$

Value: $x = f(x_1 x_2 \dots)$

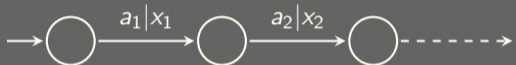
Value functions

Inf, Sup, LimInf, LimSup

LimInfAvg, LimSupAvg, DSum

Quantitative Automata

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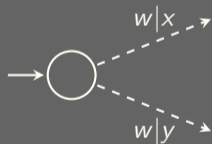
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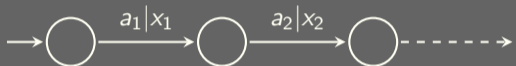
Non-determinism



$A(w) = \sup\{\text{values of } w\text{'s runs}\}$

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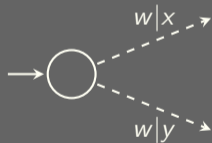
Subset of quantitative properties

- ▶ totally ordered domain

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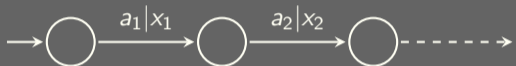
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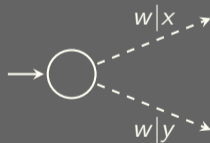
Subset of quantitative properties

- ▶ totally ordered domain
- ▶ finitely many weights

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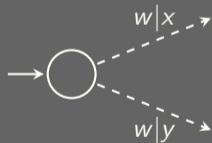
- ▶ totally ordered domain
- ▶ finitely many weights
- ▶ supremum-closed

$$\forall u \in \Sigma^* : \sup_{v \in \Sigma^\omega} A(uv) \in \{A(uv') : v' \in \Sigma^\omega\}$$

Value functions

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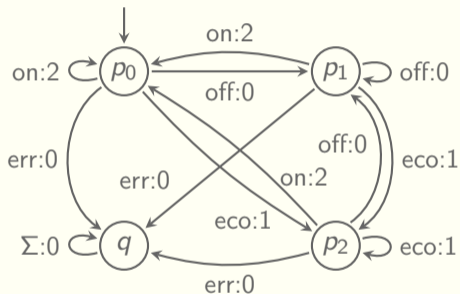
Non-determinism



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Example of LimSup Automaton

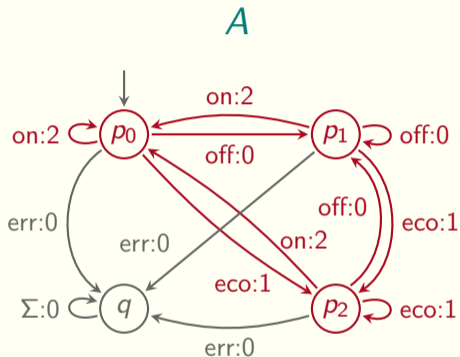
A



$w = \text{off on eco off eco off eco} \dots \text{off eco} \dots$

$A(w) = \text{LimSup } 0210101 \dots 01 \dots = 1$

Example of LimSup Automaton



No Error

$$\forall u \in (\Sigma \setminus \{\text{err}\})^* : A(u \text{ on}^\omega) = 2$$

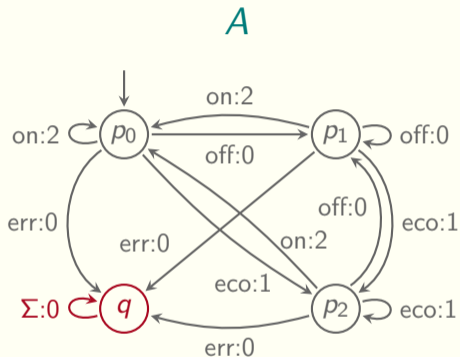
$$\forall u \in (\Sigma \setminus \{\text{err}\})^* : A(u \text{ eco}^\omega) = 1$$

$$\forall u \in (\Sigma \setminus \{\text{err}\})^* : A(u \text{ off}^\omega) = 0$$

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After Error

$$\forall v \in \Sigma^\omega : A(\text{err } v) = 0$$

$w = \text{off on eco off eco off eco} \dots \text{off eco} \dots$

$$A(w) = \text{LimSup } 0210101 \dots 01 \dots = 1$$

Boolean Safety

Intuition

Every **wrong** hypothesis $w \in \Phi$ can always be rejected after a finite number of observations

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Example: Requests Not Duplicated

- ▶ $\Sigma = \{r, g, t, o\}$ r : request, g : grant, t : clock-tick, o : other
- ▶ $\Phi =$ no r is followed by another r without some g in between

$w =$ `t r t o t t o g t o o r t t o r t t o g t r ...`
 $w \in \Phi:$ `T F`

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Definition

A boolean property $\Phi \subseteq \Sigma^\omega$ is safe when

$$\forall w \in \Sigma^\omega : w \notin \Phi \implies \exists u \sqsubseteq w : \forall v \in \Sigma^\omega : uv \notin \Phi$$

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Example: Minimal Response Time

- ▶ $\Sigma = \{r, g, t, o\}$ r: request, g: grant, t: clock-tick, o: other
- ▶ $\Phi_{\min}(w)$ = greatest lower bound on the occurrences of t between all matching r/g in w

$w =$ t r t o t t o g t o o r t t o **r t t o g** t r ...
 $\Phi(w) \geq 3:$ T F

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⁴ Henzinger, Mazzocchi, Saraç. *Quantitative Safety and Liveness*. 2023

Safety of Quantitative Automata

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Threshold safety

A quantitative property $\Phi : \Sigma^\omega \rightarrow \mathbb{D}$ is threshold-safe when

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Theorem: For totally ordered domain, threshold-safety = quantitative safety

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The safety closure Φ^* is the least safety property that bound Φ from above

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least upper bound: $\infty \dots 3 \dots \dots \dots 2 \dots \dots$

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Example: Minimal Response Time

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Definition⁵

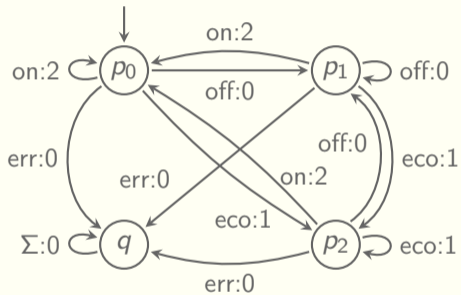
Given $\Phi : \Sigma^\omega \rightarrow \mathbb{D}$, its safety closure is $\Phi^*(w) := \inf_{u \sqsubseteq w} \sup_{v \in \Sigma^\omega} \Phi(uv)$ for all $w \in \Sigma^\omega$

Theorem⁵: Φ is safe $\iff \Phi = \Phi^*$

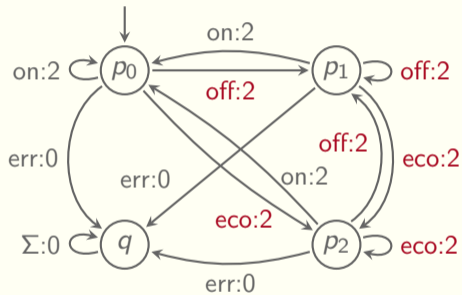
⁵ Henzinger, Mazzocchi, Saraç. *Quantitative Safety and Liveness*. 2023

Example of Safety Closure

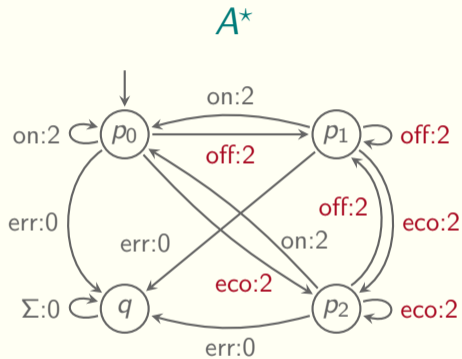
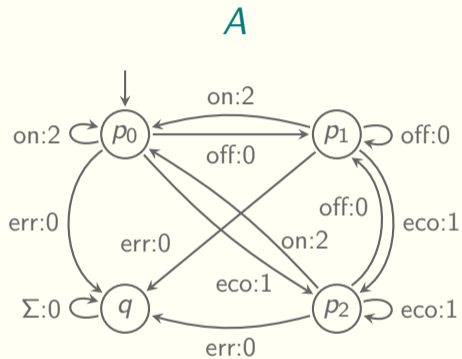
A



A^*



Example of Safety Closure



A is not safe since $A \neq A^*$ as witnessed by $A(\text{eco}^\omega) = 1$, $A^*(\text{eco}^\omega) = 2$

Deciding Safety

Reduction to language equivalence problem

Classes of Sup, LimInf and LimSup are decidable for equivalence: **determine whether $A = A^*$**

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Classes of Inf and DSum automata contain only safe automata: **safety is trivial**

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About LimInfAvg and LimSupAvg

- ▶ $\text{Avg}(x_1x_2\dots) - \text{Avg}(y_1y_2\dots) \neq \text{Avg}((x_1 - y_1)(x_2 - y_2)\dots)$

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Theorem: Safety is decidable for Inf, Sup, LimInf, LimSup, Avg, and DSum automata

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Some **wrong** hypothesis $w \in \Phi$ can never be rejected after any finite number of observations

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Example: All Requests Granted

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Example: Average Response Time

- ▶ $\Sigma = \{r, g, t, o\}$
- ▶ $\Phi_{\text{avg}}(w) =$ average on the occurrences of t between all matching r/g in w

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$\Phi(w) \geq 3:$ T.....?...

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Example: Average Response Time

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Definition⁶

A quantitative property $\Phi : \Sigma^\omega \rightarrow \mathbb{D}$ is live when

$$\forall w \in \Sigma^\omega : \Phi(w) < \top \implies \exists x \in \mathbb{D} : \Phi(w) \not\geq x \wedge \forall u \sqsubseteq w : \sup_{v \in \Sigma^\omega} \Phi(uv) \geq x$$

⁶ Henzinger, Mazzocchi, Saraç. *Quantitative Safety and Liveness*. 2023

Liveness of Quantitative Automata

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Theorem: A property Φ is threshold live iff the set $\{w \in \Sigma^\omega \mid \Phi(w) = \top\}$ is dense

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A quantitative property $\Phi : \Sigma^\omega \rightarrow \mathbb{D}$ is top-live when $\Phi^*(w) = \top$ for all $w \in \Sigma^\omega$

Theorem: For supremum-closed properties, top-liveness = threshold-liveness = liveness

Deciding Liveness

Reduction to constant function problem

All classes are decidable for the constant function problem: **determine whether $A^* = \top$**

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About DSum

- ▶ Every DSum automaton equals its safety closure: **determine whether $A = \top$**

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- ▶ Determine the highest achievable value of each state

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- ▶ Determine the highest achievable value of each state
- ▶ Trim transitions that do not lead to the highest value of the source state

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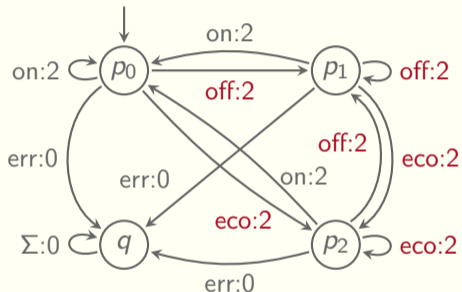
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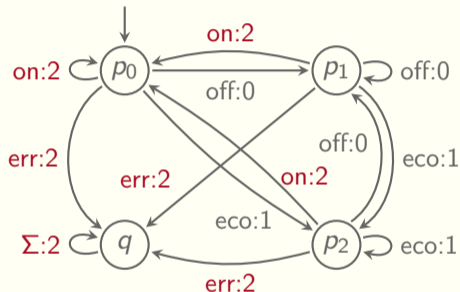
Theorem: Liveness is decidable for Inf, Sup, LimInf, LimSup, Avg, and DSum automata

Example of Safety-Liveness Decomposition

$$A_{\text{safe}} = A^*$$



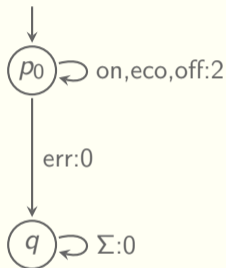
$$A_{\text{live}}$$



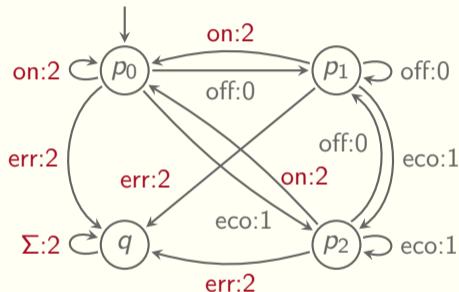
construction for **deterministic** for Sup, LimInf, and LimSup automata

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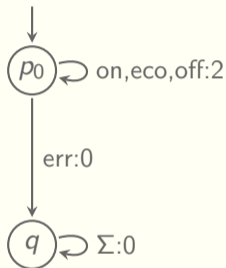
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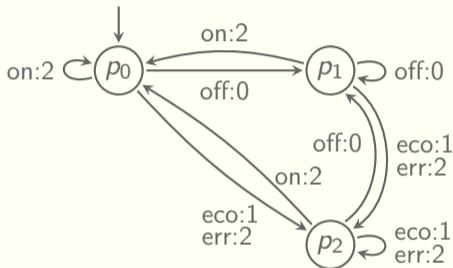
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In a nutshell

	Inf	Sup, LimInf, LimSup	LimInfAvg, LimSupAvg	DSum
Safety Closure construct A^*	$O(1)$	P _{TIME}		$O(1)$
Is A constant? i.e., $A = \top$	P _{SPACE} -complete			
Is A safe? i.e., $A^* = A$	$O(1)$	P _{SPACE} -complete	EXP _{SPACE} P _{SPACE} -hard	$O(1)$
Is A live? i.e., $A^* = \top$	P _{SPACE} -complete			
Decomposition construct $A_{\text{safe}} A_{\text{live}}$	$O(1)$	P _{TIME} if deterministic	Open	$O(1)$

In a nutshell

	Inf	Sup, LimInf, LimSup	LimInfAvg, LimSupAvg	DSum
Safety Closure construct A^*	$O(1)$	P _{TIME}		$O(1)$
Is A constant? i.e., $A = \top$	P _{SPACE} -complete			
Is A safe? i.e., $A^* = A$	$O(1)$	P _{SPACE} -complete	EXP _{SPACE} P _{SPACE} -hard	$O(1)$
Is A live? i.e., $A^* = \top$	P _{SPACE} -complete			
Decomposition construct $A_{\text{safe}} A_{\text{live}}$	$O(1)$	P _{TIME} if deterministic	Open	$O(1)$

Thank you