#### TACAS 2025 - Hamilton Canada

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# **Automating** the Analysis of Quantitative Automata with QuAK

# **Boolean Setting**



#### **Definition**

A Boolean property  $\Phi \subseteq \Sigma^{\omega}$  or equivalently  $\Phi \colon \Sigma^{\omega} \to \{0,1\}$ , is a language

# Safety Requests Not Duplicated



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# Safety

Requests Not Duplicated

# Liveness

All Requests Granted

# Theorem: Decomposition<sup>1</sup>

All Boolean property  $\Phi$  can be expressed by  $\Phi = \Phi_{\mathsf{safe}} \cap \Phi_{\mathsf{live}}$ 

 $\Phi_{\rm safe}$  is safe

 $\Phi_{live}$  is live

<sup>&</sup>lt;sup>1</sup> Alpern, Schneider. Defining liveness. 1985

# **Quantitative Setting**



#### **Definition**

A quantitative property  $^2 \Phi \colon \Sigma^\omega o \mathbb{D}$  is a quantitative language where  $\mathbb{D}$  is a complete lattice

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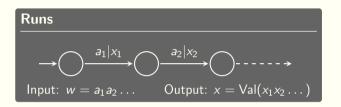
# Theorem: Decomposition<sup>3</sup>

All quantitative property  $\Phi$  can be expressed by  $\Phi(w) = \min\{\Phi_{safe}(w), \Phi_{live}(w)\}$  for all  $w \in \Sigma^{\omega}$   $\Phi_{safe} \text{ is quantitative safe}$   $\Phi_{live} \text{ is quantitative live}$ 

<sup>&</sup>lt;sup>3</sup> Henzinger, Mazzocchi, Saraç. *Quantitative Safety and Liveness*. 2023

# **Quantitative Automata**



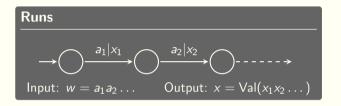


#### Value function Val

Inf, Sup, LimInf, LimSup LimInfAvg, LimSupAvg

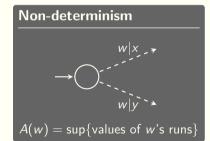
# **Quantitative Automata**





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# **Quantitative Automata**



# Runs $\xrightarrow{a_1|x_1} \xrightarrow{a_2|x_2} \xrightarrow{----}$ Input: $w = a_1 a_2 \dots$ Output: $x = Val(x_1 x_2 \dots)$

# **Subset of quantitative properties**<sup>4</sup>

- $\Phi \colon \Sigma^\omega \to \mathbb{D}$  where  $\mathbb{D}$  is a complete lattice
- totally ordered domain
- finitely many weights
- supremum-closed

#### Value function Val

Inf, Sup, LimInf, LimSup LimInfAvg, LimSupAvg

# Non-determinism |w|x |x| |w|y |x| |x|

<sup>&</sup>lt;sup>4</sup> Chatterjee, Doyen, Henzinger. *Quantitative Languages*. 2010



#### Intuition

Every **wrong** hypothesis  $\Phi(w) \ge x$  can always be rejected after a finite number of observations



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#### **Example: Minimal Response Time**

- $ightarrow \Sigma = \{r, g, t, o\}$  r: request, g: grant, t: clock-tick, o: other
- $m{\Phi}_{\sf min}(w) = {\sf greatest}$  lower bound on the occurrences of t between all matching  ${f r}/{f g}$  in w



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# **Definition**<sup>5</sup>: A quantitative property $\Phi: \Sigma^{\omega} \to \mathbb{D}$ is safe when

$$\forall x \in \mathbb{D} : \forall w \in \Sigma^{\omega} : \varPhi(w) \not \geq x \implies \exists u \sqsubseteq w : \sup_{v \in \Sigma^{\omega}} \varPhi(uv) \not \geq x$$



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**Theorem**<sup>5</sup>:  $\Phi$  is safe  $\iff \Phi = \Phi^*$  where  $\Phi^*$  is the safety closure of  $\Phi$ 

<sup>&</sup>lt;sup>5</sup> Henzinger, Mazzocchi, Saraç. *Quantitative Safety and Liveness*. 2023



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# **Example: Average Response Time**

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- $arPhi_{\mathsf{avg}}(w) = \mathsf{average}$  on the occurrences of t between all matching  $r/\mathsf{g}$  in w



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# **Definition**<sup>6</sup>: A quantitative property $\Phi: \Sigma^{\omega} \to \mathbb{D}$ is live when

$$\forall w \in \Sigma^{\omega} : \Phi(w) < \top \implies \exists x \in \mathbb{D} : \Phi(w) \not\geq x \land \forall u \sqsubseteq w : \sup_{v \in \Sigma^{\omega}} \Phi(uv) \geq x$$



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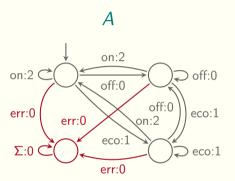
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**Theorem**<sup>6</sup>:  $\Phi$  is live  $\iff \forall w : \Phi^*(w) = \top$  where  $\Phi$  is supremum closed

<sup>&</sup>lt;sup>6</sup> Henzinger, Mazzocchi, Saraç. Quantitative Safety and Liveness. 2023

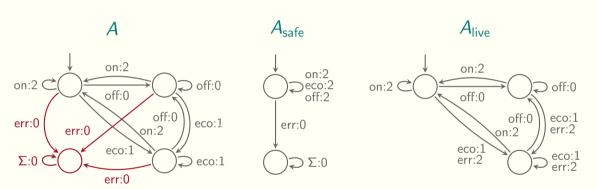
# **Safety-Liveness Decomposition**





# **Safety-Liveness Decomposition**





$$A(w) = \min\{A_{\mathsf{safe}}(w), A_{\mathsf{live}}(w)\}$$

# QuAK's Library



|                      | Input | Problem   | Val        |
|----------------------|-------|---|------------|
| Top value ⊤          | А     | $	op = \sup\{A(w): w \in \Sigma^\omega\}$                                   | -          |
| Bottom value ⊥       | А     | $\perp = \inf\{A(w) : w \in \Sigma^{\omega}\}$                              |            |
| Safety closure $A^*$ | А     | Least safe over approximation of $A$ -                                      |            |
| Non-emptiness        | A, x  | $\exists w \in \Sigma^{\omega} : A(w) \geq x \iff \top \geq x$              | -          |
| Universality         | A, x  | $\forall w \in \Sigma^{\omega} : A(w) \geq x \iff \bot \geq x$              | $\neq Avg$ |
| Inclusion            | A, B  | $\forall w \in \Sigma^{\omega} : A(w) \geq B(w)$                            |            |
| Constant             | Α     | $\forall w \in \Sigma^{\omega} : A(w_1) = \top$                             |            |
| Safety               | Α     | $\forall w \in \Sigma^{\omega} : A^{\star}(w) = A(w)$                       |            |
| Liveness             | Α     | $\forall w \in \Sigma^{\omega} : A^{\star}(w) = \top$                       |            |
| Decomposition        | Α     | $\forall w \in \Sigma^{\omega} : A(w) = \min\{A_{safe}(w), A_{live}(w)\}$ - |            |

# **QuAK's Library**



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# **Complexities**



|                             | Inf                           | Sup, LimInf, LimSup | LimInfAvg, LimSupAvg    |  |  |
|-----------------------------|-------------------------------|---------------------|-------------------------|--|--|
| Is A non-empty?             | PTIME                         |                     |                         |  |  |
| i.e., $\top \geq x$         | F 1 IME                       |                     |                         |  |  |
| Is A universal?             | Р                             | SPACE-complete      | Undecidable             |  |  |
| i.e., $\perp \geq x$        | 1 SPACE-complete Officeduable |                     |                         |  |  |
| Is A constant? <sup>7</sup> | PSpace-complete               |                     |                         |  |  |
| i.e., $\top = A = \bot$     | 1 SPACE-Complete              |                     |                         |  |  |
| Is A safe? <sup>7</sup>     | O(1)                          | PSPACE-complete     | EXPSPACE \ PSPACE-hard  |  |  |
| i.e., $A^* = A$             |                               |                     | EXPSPACE \ 1 SPACE-Haid |  |  |
| Is A live? <sup>7</sup>     | PSPACE-complete               |                     |                         |  |  |
| i.e., $A^\star = \top$      | r SPACE-complete              |                     |                         |  |  |

<sup>&</sup>lt;sup>7</sup> Boker, Henzinger, Mazzocchi, Saraç. Safety and Liveness of Quantitative Automata. 2023



# **Efficient constant testing**

▶ Constant check without relying on the limitedness of distance automata<sup>8</sup>



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#### **Exhaustive decomposition framework**

 PTIME safety-liveness decomposition for all quantitative automata (including LimSup, LimInfAvg and LimSupAvg automata previously left open 10)

<sup>10</sup> Boker, Henzinger, Mazzocchi, Saraç. Safety and Liveness of Quantitative Automata. 2023

Nicolas Mazzocchi funding: ERC-2020-AdG 101020093



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# Thank you